Analysis of Fracture Behavior of Ceramics by Generallized Multimodal Weibull Function

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ABSTRACT

A new concept-generallized multimodal Weibull function-is presented based on the competing risk theory and fracture mechanics. As the case which has only one random variable, the distribution functions of fast-fracture strength, dynamic fatigue strength and cyclic fatigue life are reviewed. As a two-variable case, the distribution functions of fracture location and crack size at fracture origin are showed using the joint probability density function with respect to fracture stress and fracture location for n fracture causes with experimental verification on HP-Si₃ N_{μ}. The newly developed theory, which involves 3 random variables-fracture stress, fracture location and flaw orientationis outlined. The method for estimating Weibull parameters, which is called as the multistep maximum likelihood method, is reviewed.

1.Introduction

Since almost all ceramics are policrystalline made by sintering process, they involve many kinds of flaws in their surfaces and inside the bodies.

Flaws which may cause fracture can be divided into three categories as follows:

- (A) intrinsic flaws
- (B) coalescing microcracks
- (C) voids, flaws developed from voids.

In low and medium temperature ranges(T<0.5Tm, Tm:melting

temperature), flaws (A) and (B) are predominant; the stressstrain relation is elastic up to fracture and strength being constant against temperature change. In high temperature ranges (T>0.5Tm), flaws (C) are predominant, the stress-strain relation is nonlinear, and strength decreases as temperature increases.

Of the three categories of major flaws that influence the strength of structural ceramics, intrinsic flaws are the most important. They can further be divided as follows:

internal	flaws: I	pores, lusion daries	pore s, in	cluste nterna:	rs, (lcrae	coarse cks,wea	garair akgrai	n, n	inc- boun-	
	- 1								-	

surface flaws: cracks caused by machining or impact damage, exposed internal flaws

When ceramic materials are subjected to some kinds of loads under a definite environment, these intrinsic flaws 'compete' each other and the most hazardous flaw of them acts as a fracture origin which leads to final fracture.

In this review, we suggest that the fracture behaviors of ceramics under some conditions can be described by generallized multimodal Weibull function. Also we suggest how important the data of fracture causes are for estimating the Weibull parameters.

2. Generallized multimodal Weibull Function

According to the competing risk theory with independent risks[1], the probability density function of random variable X involving k fracture causes can be formulated by the following equation;

$$f(X) = \prod_{i=1}^{k} \operatorname{Ri} \cdot \sum_{j=1}^{k} \lambda_{j}$$
(1)

where Ri and λj are the reliability function (or survival probability function) and the failure rate of i-th (or j-th) cause of fracture, respectively. We must note that the random variable X in Eq.(1) may be a vector; namely, Eq.(1) may be a multi-variable joint probability density function. We call Eq.(1) as the generallized multimodal Weibull function — as long as the strength (or life-time) distribution derived from Eq.(1), as a marginal, is a multimodal (or uni-modal) Weibull distribution function.

In the following we discuss about some probability density functions or probability distribution functions in those cases which involve up to 3 random variables.

2.1 One-variable case

Fast fracture strength

According to the weakest link theory, the distribution function of the fast-fracture strength (ϕ_n) must obey so-called multimodal Weibull distribution function, which was derived from a competing risk model expressed by Eq.(1), written as

$$E(\phi) = \sum_{i=1}^{k} Bi - \exp[-\sum_{i=1}^{k} Bi]$$
(2)

where Bi: risk of rupture due to the i-th fracture cause and k: number of different fracture causes.

Now let us suppose that a test piece has a stress gradient and internal(i=1), surface(i=2) and edge(i=3) cracks for fracture causes. Then, for uniaxial Weibull distibution functions (functions applicable to uniaxial stress), we have Bi as follows:

$$B1 = \int_{V} \left(\frac{\sigma - \sigma_{u_1}}{\sigma_{o_1}} \right)^{m_1} dV, \quad B2 = \int_{A} \left(\frac{\sigma - \sigma_{u_2}}{\sigma_{o_2}} \right)^{m_2} dA, \quad B3 = \int_{V} \left(\frac{\sigma - \sigma_{u_3}}{\sigma_{o_3}} \right)^{m_3} dL \quad (3)$$

where dV,dA and dL are nondimensional volume, surface, and line
elements, respectively, and mi, 60i, 6ui are Weibull parameters.

Also, for distribution functions applicable to the multiaxial stress state (multiaxial distribution function), Bi is given by [2] $B_{1} = \frac{2}{\pi} \int_{V} \int_{0}^{\frac{\pi}{2}} \int_{0}^{\frac{\pi}{2}} \left(\frac{Z_{1} - \sigma_{n_{1}}}{\sigma_{0_{1}}} \right)^{m_{1}} \cdot Y(Z_{1}, \sigma_{n_{1}}) \qquad B_{2} = \frac{2}{\pi} \int_{A} \int_{0}^{\frac{\pi}{2}} \left(\frac{Z_{2} - \sigma_{n_{1}}}{\sigma_{0_{2}}} \right)^{m_{2}} \cdot Y(Z_{1}, \sigma_{n_{2}}) d\theta \, d\Lambda$ $sin\phi \, d\phi \, d\theta \, dV \qquad B_{3} = \int_{L} \left(\frac{Z_{3} - \sigma_{n_{3}}}{\sigma_{0_{3}}} \right)^{m_{3}} \cdot Y(Z_{3}, \sigma_{n_{3}}) dL \qquad (4)$

where Zi is a guantity derived from unstable crack extension conditions in a mixed mode and called an equivalent normal stress, and defined by

$$Zi = \frac{K_{IC}}{Y_{i}\sqrt{LC}}$$
(5)

where c: representative crack length, K1c: fracture toughness and Yi: geometric constant. Equation (4) is very useful for designing brittle-structural components based on statistical analysis. We can also estimate the brittle fracture loci under biaxial or triaxial stress states (see Fig.1)[3,4] and the fracture behavior of ceramics with ground surfaces (see Fig.2)[5,6].

Dynamic fatigue strength and cyclic fatigue life

Assuming that the following slow crack growth law is dominant in almost the whole life time of the stressed material under a certain environment.

$$da/dt = AK1^{\prime\prime}$$
 (6)

where da/dt is the crack growth rate, A and n are crack-growth parameters, and K1 is a stress intensity factor. Combining the inert strength distribution (=fast fracture strength), expressed

by multimodal Weibull function (Eq.(3)), with above slow crack growth law, we can obtain the distribution functions of static and cyclic fatigue life and of dynamic fatigue strength.

For simplicity, in the following, suppose that $\delta ui=0$. Let $\delta 1(>0)$ be the maximum principal stress at any point of the material, and

is expressed by

$$\delta 1 = \delta \cdot g(r) t = \delta m \cdot g(r)$$
(7)

where r is a position vector, σ is a constant stress rate, σ is a representative stress (e.g. the maximum stress), g(r) is a nondimensional scalar function of the position vector,t is a time. Then, the risks of rupture for dynamic fatigue strength can be expressed by the following equations[7].

$$Bi = (\delta m / \delta o i)^{r_{k}} [Aeff]i$$
(8)

where mi and ooi are "mapped" Weibull parameters given by

$$m_{i}' = \frac{n_{i}+1}{n_{i}-2} m_{i}, \quad \overline{\sigma_{0i}} = \overline{\sigma_{0i}} \left(\beta_{i}(n_{i}+1)\sigma\right)^{\frac{1}{n_{i}-2}}, \quad \beta_{i} = 2\left[(n_{i}-2)AY^{2}K_{i}c^{\frac{n_{i}-2}{2}}\right]^{-1} \quad (9)$$

Here, [Aeff]i is a nondimensional effective volume, surface area or length of edges, expressed as

$$[Aeff]i = \begin{pmatrix} ni ni / (ni-2) \\ g(r) \\ Ai \end{pmatrix}$$
(10)

where Ai represents the domain of the i-th fracture cause and dAi is an infinitesimal volume, surface or line element.

Figure 3 shows the Weibull plots of the bending strength of steatite ceramics under the constant stress rate $\sigma = 2,74$ MPa/sec by using mean rank method(surface flaws). The dotted line(three-point bend, in air) and the broken line (four-point bend, in vacuum) in the figure are the theoretical curves calculated from Eqs.(2),(8) and (9). These curves coincide fairly well with the experimental results.

Almost the same stream line, we obtain the risks of rupture for cyclic fatigue life of ceramics. In this case, we suppose that the maximum principal stress at any point of the material is periodic and can be written by

$$\delta 1 = \delta m \cdot g(r) \cdot h(wt), w: angular velocity (11)$$

where h(wt) is a function of wt, for example, a sine wave. Then, the risk of rupture of cyclic fatigue life ,Nrep, is expressed as [8]

where m_{N1} and Noi are also "mapped" Weibull parameters given by

$$m_{Ni} = \frac{1}{n_{i}-2} \cdot m_{i}$$

$$N_{oi} = \frac{\beta_{i}}{\sigma_{m}^{n_{i}} \int_{0}^{2\pi/\omega} h(\omega t)^{n_{i}} dt} \cdot \sigma_{oi}^{n_{i}-2}$$

$$\frac{2.2 \text{ Two variables}}{\sigma_{m}^{n_{i}} \int_{0}^{2\pi/\omega} h(\omega t)^{n_{i}} dt} \cdot \sigma_{oi}^{n_{i}-2}$$

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Let introduce a random-variable vector

$$X = (6m, \xi)$$

where δm is a representative stress (inert strength) and \mathfrak{f} a fracture location. According to Oh and Finnie[9], when a body is subjected to a representative stress in a range ($\delta m, \delta m + d \delta m$) and fails at a location \mathfrak{f} by i-th fracture cause, the joint probability density function $hA_{i}(\delta m, \mathfrak{f})$ can be written as

$$h_{Ai}(f_m,\xi)d\xi df_m = \exp(-Bi)\frac{\partial}{\partial f_m}(Gi)d\xi df_m \qquad (14)$$

where Ai is a domain of i-th fracture cause, Bi is the risk of rupture due to i-th fracture cause and Gi is a function of Bi and §. Then Bi and Gi for Weibull's uniaxial distribution function can be written as

$$Bi = \int_{\xi} G_{i} d\xi, \quad G_{i} = \left(\frac{\sigma_{i} - \sigma_{ui}}{\sigma_{vi}}\right)^{m_{i}} Y(\sigma_{i}, \sigma_{ui}) \left(\frac{dA_{i}}{d\xi}\right) \quad (15)$$

where Y(,) is Heaviside's step function.

Combining Eq.(14) with the competing risk theory expressed by Eq.(1), the joint probability density function $h_{A}(\delta m, \xi)$ involving K fracture causes can be formulated as[10]

$$h_{A}(\sigma_{m}, \xi) = \prod_{i=1}^{K} R_{i}(\sigma_{m}) \cdot \sum_{j=1}^{K} \lambda_{j}$$
(16)

where Ri and λ j are given as

 $Ri(\sigma_m) = 1 - \int_0^{\sigma_m} \int_{\xi \in h_{Ai}} (\sigma_m, \xi) d\xi d\sigma_m, \qquad (17)$

 $\lambda j = h_{A_1}(\sigma m, \xi) / R_j(\sigma m), A = A_1 \oplus A_2 \oplus --- \oplus A_K$

Here, \int_{ξ_t} represents the integration over the total domain of Ai; the (f) symbol indicates "direct sum" used in set theory.

From Eqs.(16) and (17), two important marginals can be derived. The marginal with respect to fracture stress of coincides with the multimodal Weibull distribution function. The other marginal with respect to fracture location ξ is of the socalled mixture type.

Analysis of diagnostic data of HP-Si Ng

Ito et al.[11] carried out the 3-point bending test to 415 HP-Si₃N₄ specimens (specimens had the following characteristics: mean grain size=2.0 μ m, surface roughness Rmax=0.8 μ m, half span L=10.0mm, width b=1.5mm, half height h=1.5mm).

They measured the fracture stress δm , the coordinates of the fracture location (x,y) and the flaw size which initiated fracture. Using these fracture stress data, the bi-modal Weibull parameters mi and $\delta 0i$ (i=1 for inner flaw, i=2 for surface flaw) have been estimated utilizing the multimaximum likelihood method (see next chapter) as shown in Table 1.

Using the estimated parameters in Table 1, we can estimate the distributions of fracture location, modified fracture stress and flaw size. Now we adopt the coordinate systems as shown in Fig.4.

Suppose that there are two types of fracture origin, namely,

inner cracks (i=1, the domain is expressed by A1) and surface cracks (i=2, the domain is expressed by A2), and that fracture does not occur at the side surfaces of a specimen.

The cumulative distribution function of the fracture location along the x axis SA1 \oplus A2 is derived below in Eq.(18); the function along the y axis UA1 \oplus A2 may be derived in a similar fashion, the result being shown in Eq.(19).

$$S_{A_{1} \bigoplus A_{2}} (X) = S_{A_{1}}(X) \cdot p_{A_{1}} + S_{A_{2}}(X) \cdot p_{A_{2}}$$

$$SA_{1}(X) = (X/L)^{m_{1}+1}, \quad S_{A_{2}}(X) = (X/L)^{m_{2}+1}$$

$$pA_{1} = \int_{0}^{\infty} dB_{1}/d\sigma_{m} \cdot exp(-B_{1}-B_{2}) d\sigma_{m}, \quad p_{A_{2}} = \int_{0}^{\infty} dB_{2}/d\sigma_{m} \cdot exp(-B_{1}-B_{2}) d\sigma_{m}$$

$$UA_{1} \oplus A_{2}(Y) = U_{A_{1}}(Y) \cdot p_{A_{1}} + U_{A_{2}}(Y) \cdot p_{A_{2}}$$

$$U_{A_{1}}(Y) = 1 - \{(h-Y)/h\}^{m_{1}+1}, \quad U_{A_{2}}(Y) = 1.$$
(19)

In Eqs.(18) and (19) pA1 and pA2 represent the cumulative fracture probabilities up to $\delta m = \infty$ in the domains A1 and A2, respectively. Thus, Eqs.(18) and (19) are of the so-called mixture type. Therefore we can separate the date of fracture location simply. In Eqs.(18), note that the relation between lnSAi(X) and ln(X/L) is linear.

The solid lines in Figs.5(a) and (b) show the individual distribution functions of fracture location calculated from Eq.(18). It can be seen that they coincide fairly well with the experimental data points, expressed by the + signs. Fig.6 shows the experimentally derived histogram relating to the y-coordinate of the depth of fracture origin. O signs connected by solid lines represent the estimated results calculated from Eq.(19); these coincide satisfactorily with the experimental results.

Distribution of Flaw Size

Suppose that the inner flaw which initiates fracture is a penny shaped crack parallel to y-z plane and that the following equation is valid, at fracture, for any crack size.

$$K_{1c} = \frac{2}{\pi} \sigma_{c} \sqrt{\pi d/2}$$
 (20)

where d is the diameter of the crack. Then we obtain

$$hA1(d,\xi) = \frac{bm_1(\frac{K1c\sqrt{\pi}}{\sqrt{2\sigma_{01}}})^{m_1}d^{-(m_1+2)/2} \cdot exp[-Veo\{\frac{K1c\sqrt{\pi}}{\sqrt{2\sigma_{01}}}, \frac{Lh}{x(h-y)\sqrt{d}}\}^{m_1}] \quad (21)$$

From this equation, we can calculate the probability density function of the crack size d as a marginal.

Fig.7 shows the histogram of observed flaw size d. In this figure, o signs connected with solid lines represent the theoretical results (K1C=4.06 MPaVm); these coincide precisely with experimental results within the range of comparatively large crack size (40-85µm).

Although the observed crack size at mode (about 35µm) coincides with that of the estimated one, the absolute value of percentage is different. It would appear that this diffence results from the assumption that K1c value is dependent of the crack size/mean grain size ratio.

Recently it was found that the fracture toughness of ceramics decreases as the ratio of the crack size versus the mean grain-size does. Usami et al.[12] deduced the following equation to explain such phenomena.

$$K_{\rm c}/K_{\rm ic} = \frac{(1+r/2 a_{\rm e})^{1/2}}{(1+r/a_{\rm e})}$$
(22)

where K1C is the plane strain fracture toughness obtained from comparatively large cracks; KC is an apparent fracture toughness for a small crack; r is the size of the weakest grain (which is taken to be twice the mean grain-size); 2de is a size of an equivalent two-dimensional straight crack. Since we assumed that there are penny shaped cracks in a body, Ge in our case is given by

Qe ⊆ 0.2dc

Substituting Kc given by Eq.(22) into K1c in Eq.(21), we obtain the joint probability density function under three-point bending load[13].

Closed circles (• signs) are the calculated results obtained from the above analysis, which coincide with the experimental results better than those of open circles (O signs). However, the calculated results expressed by ! signs over-estimate the flaw-size in the region dc>50µm. Therefore, from the view point of the structural reliability, the analysis using K1C is better than that using Eq.(22).

2.3 Three variables

In the theory explained in section 2.2, we supposed that the penny-shaped crack which might cause fracture should lie perpendicular to the maximum principal stress. However, the crack which may cause fracture does not always lie as thus. If we want to know the flaw-orientation distribution as well as those of fracture stress, flaw-size and flaw location, we have to adopt the multiaxial Weibull distribution function instead of uni-axial one.

Let intoduce a random-variable vector as

$$X = (\mathcal{T}_{m}, \boldsymbol{\xi}, \boldsymbol{\alpha}) \tag{23}$$

then we obtain the three-variable joint probability density

function as [14].

hAi
$$(\overline{\mathcal{T}}_{n}, \overline{\mathcal{T}}, d)$$
 dd d $\overline{\mathcal{T}}_{dm} = \exp(-B_{i})\frac{\partial}{\partial \overline{\mathcal{T}}_{m}}(\overline{\mathcal{T}}_{i})$ dd d $\overline{\mathcal{T}}_{dm}$, (24)
Bi = $\int_{\overline{\mathcal{T}}_{t}} \left(\int_{d+1}^{d+1} dd d\overline{\mathcal{T}}_{d} , G_{i} = \frac{1}{\overline{\mathcal{T}}_{t}} \left(\frac{\overline{Z_{i}} - \overline{\mathcal{T}}_{u}}{\overline{\mathcal{T}}_{u}} \right)^{n_{i}} Y(\overline{Z_{i}}, \overline{\mathcal{T}}_{u}) \left(\frac{dA_{i}}{dd} \right) \left(\frac{dA_{i}}{d\overline{\mathcal{T}}} \right).$

where, the subscript t means the total domain of each variable; dà is a surface element of a unit sphere. In general, ϕ is a 2dimensional vector which has two independent components related to the space angles, say θ and ϕ (see Fig.8).

Similar to Eq.(16), the joint probability density function $hA(Gm,\xi,d)$ involving K causes of fracture can be formulated as

$$hA(Om, \mathfrak{F}, \mathfrak{c}) = \frac{\kappa}{1!} R_{i} \cdot \frac{\kappa}{\sigma} \lambda_{j},$$

$$Ri = 1 - \int_{\mathfrak{D}}^{\mathfrak{O}m} \int_{\mathfrak{F}_{t}} \int_{\mathfrak{c}t} h_{A_{i}}(\mathfrak{O}m, \mathfrak{F}, \mathfrak{c}) d\mathfrak{c} d\mathfrak{F} d\mathfrak{O}m, \qquad (25)$$

$$\lambda i = h_{A_{i}}(\mathfrak{O}m, \mathfrak{F}, \mathfrak{c}) / R_{i},$$

$$A = A_{1} \oplus A_{2} \oplus \cdots \oplus A_{K}.$$

Equation (25) is valid for an arbitrary stress state and arbitrary types of fracture origins.

Using the general equation derived in the above, we analyse the 3-point bending test of a rectangular cross-sectioned ceramic specimen (see Fig.4).

For simplicity, we suppose that there is only one type of fracture origin, namely, penny-shaped crack. For the first step, we employ the shear insensitive criteria as a mixed mode fracture criteria.

In the analysis it is assumed that the crack plane is perpendicular to the thickness direction of a specimen. Therefore, $d\mathbf{x}=d\boldsymbol{\phi}$.

The distribution function of flaw-orientation is obtained as the marginal with respect to flaw-orientation angle ϕ as

$$HA1(\phi) = 1 - \cos^{2m_{1}+1}\phi$$
 (26)

which leads to the following density function.

$$hA1(\phi) = (2m_1 + 1) \sin\phi \cdot 600^{2m_1} \phi \qquad (27)$$

Fig.9 shows the calculated flaw-orientation distribution function and the density function. From these figures we see that the flaw-orientation distribution shifts toward low angle and becomes sharp as m value increases. These mean that the smaller the scatterness of fracture strength becomes, the smaller the flaw-orientation angle does. It is without saying that the probability density function is strongly influenced by the fracture criteria[14]. The analysis mentioned above, including those of the previous section , may play an important role on non-destructive inspection of ceramic component[15].

3. Estimation of Webull Parameters

One of the most important factors in statistical analysis using multimodal Weibull distribution may be the problem as to how accurately the parameters can be estimated, how accurate the parameters obtained are, and how many samples are necessary. The method for estimating Weibull parameters is outlined below.

Multimodal-Weibull distribution containes a number of parameters (mi, Goi, Gui). It is known that although, by the nature of its mathematical structure, we can estimate parameters of multimodal-Weibull distribution by directly maximizing the likelihood function, its estimation accuracy is very low. However, its accuracy can be raised significantly by using fracture cause data [16]. If parameters can be estimated with such high accuracy, the information thus obtained can be fed back to material design.

Multistep maximum-likelihood method

According to competing risk theory, the likelihood function for data (complete data) on known strength and fracture causes, which are known to conform to the multimodal-Weibull distribution, is given by [16,17]: $L=Const. \times \prod_{i=1}^{k} L_{i}. \ L_{i} = [\prod_{j=1}^{ni} f_{i}(x_{ij})]$

$$\begin{bmatrix} k & n \\ r_{1} & r_{1} \\ r_{2} & r_{1} \\ r_{2} & r_{1} \\ r_{2} & r_{1} \end{bmatrix},$$
(28)

R_i=exp(-B_i), f_i=B_i' exp(-B_i) where i: type of fracture cause, ni: number of test pieces fractured by fracture cause i and Xij (i=1,..., k:j=1,..., ni): strength data for jth of test pieces fractured by fracture causes i. Li in the above equation contains only single-distribution fi. Thus, a set of parameters which maximize Li is the maximum likelihood estimates. With Oui=0, each maximum likelihood equation is expressed by $\int_{0i}^{\infty} = \left(\frac{(Aeth)}{n_i}\sum_{j=1}^{n}\chi_j^{m_i}\right)^{1/m_i}, \frac{n_i}{m_i} + \sum_{j=1}^{n}\ln\chi_j - n_i \frac{\sum_{j=1}^{n}\chi_j^{m_i}}{\sum_{j=1}^{n}\chi_j^{m_i}}, n = \sum_{j=1}^{k}n_i$ (29) Thus mi and Gui can be obtained. This is called a multistep maximum-likelihood method.

Ito et al.[11] conducted an HP-Si3N4 (3x3x28mm) 3-point bending test, as mentioned previously, producing the following results: 326 internally fractured, 77 surface fractured and 12 undetermined from total of 415 test pieces. Figure 10 shows the results of Weibull plotting of the above results[10] in accordance with fracture causes by using the Johnson method[18]. The solid line in the figure is a theoretical curve calculated by using parameter estimates (m1=15.79, 601=95.99, m2=12.73 and 6_{02} =129.5) obtained by the multistep maximum likelihood method. It agrees well with the values measured.

In addition, with some unknown fracture cause data involved, the parameters can still be estimated with high accuracy by using the improved EM algorithm[16].

<u>Relationship Between Distribution of Parameter Estimates and</u> <u>Number of Samples</u>

Let us write the maximum-likelihood estimates for parameters m and ζ contained in multimodal Weibull distribution function as \widehat{m} and $\widehat{\zeta}$, respectively. It is known that if the number n of samples is large, the distribution of \widehat{m}/m conforms to a normal one with mean 1 and variance: 0.608/n. For example, with n=25 or 50, the coefficient of variation for \widehat{m} is as follows:

$$n=25 : cov = \sqrt{\frac{0.603}{25}} = 0.156$$
$$n=50 : cov = \sqrt{\frac{0.603}{55}} = 0.110$$

Thus, with the coefficient of variation for $\widehat{\mathbf{m}}$ necessary for designing given, the necessary number of samples can be determined.

If the number of samples is small, the distribution of estimates, both unimodal- and multimodal- Weibull distributions, can be known only by using Monte Carlo simulation.

4. Conclusions

The generallized multimodal Weibull function, which is a function of a random variable vector, was presented by combining the competing risk theory and fracture mechanics. Three special cases were shown; the first are the distribution functions of fast-fracture strength, dynamic fatigue strength and cyclic fatigue life as the case which has only one random variable (one dimensional case); the second are those of fracture stress and fracture location or crack size at fracture origin as the case which has two random variables (two dimensional case); the third has three-random variables, namely, fracture strength, fracture location and flaw-orientation (three-dimensional case). The calculated results satisfactorily coincided with the experimental results carried out on HP-Si₃Nq by Ito et al..

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Fig.1 Fracture loci under bi-axial stress state (a)Alumina by S.M.Broutman et al.(1972), (b) Graphite by R.Ely (1965), (c) Cast iron by I.Cornet and R.C.Grassi (1955). The solid lines are calculated from Eq.(4).



Fig.2 Effect of the grinding direction on 4-point bending strength and expected value calculated from Eq.(4).



Fig.3 Weibull plots of the experimental results on steatite ceramics under the stress rate o=2.74 MPa/sec.



Fig.4 A rectangular cross-sectioned specimen subjected to the 3-point bending load and the coordinate systems.



Fig.5 Plots of the fracture probability S(x) and the fracture location ratio x/L on log-log scale graph paper. The solid lines are the estimeted values calculated from Eq. (18) (HP-Si N [11]).



Depth of fracture origin (µm), 4

Fig.6 Histogram of the depth of inner fracture origin relating to the y-coordinate (HP-Si N [11], o signs are the calculated results from Eq.(19).



Fig.7 Eistogram of flaw-size for 3-point bending cf EF-Si N [11] (o signs: Kc=K1c, o signs: Eq.(22)).



Fig.8 Coordinate systems used in the analysis



Fig.9 Flaw-orientation distribution (shear insensitive)



Fig.10 Weibull plots of the fracture stress o max (HP-Si N [11]) according to Johnson method[18]. The solid lines are the calculated results using competing risk theory. oc is a corrected fracture stress at fracture origin, which can be estimated from Eq.(16).

	, mi	σ _{0i}
Inner fracture (i=1)	15.79	959.9
Surface fracture (i=2)	12.73	12 95

Table 1.	Weibull	parameters	estimated	by	the	multi-maximum
	likelihood method (M-MLE).					